

- Drive
- Data
- Sensing
- LEDs
- Events
- Operators
- Sound
- Control
- Comment

forwards for 1 cm at speed 5

backwards for 1 cm at speed 5

spin left for 1 degrees at speed 5

spin right for 1 degrees at speed 5

forwards until at speed 5

backwards until at speed 5

spin left until at speed 5

spin right until at speed 5

set both motors to drive forwards at speed 5

set right motor to forwards at speed 5

set left motor to forwards at speed 5

Start

forwards for 2.6 cm at speed 5

- Drive
- Data
- Sensing
- LEDs
- Events
- Operators
- Sound
- Control
- Comment

forwards for 1 cm at speed 5

backwards for 1 cm at speed 5

spin left for 1 degrees at speed 5

spin right for 1 degrees at speed 5

forwards until at speed 5

backwards until at speed 5

spin left until at speed 5

spin right until at speed 5

set both motors to drive forwards at speed 5

set right motor to forwards at speed 5

set left motor to forwards at speed 5

Start

forwards for 10.5 inch at speed 5

- Drive
- Data
- Sensing
- LEDs
- Events
- Operators
- Sound
- Control
- Comment

forwards for 1 cm at speed 5

backwards for 1 cm at speed 5

spin left for 1 degrees at speed 5

spin right for 1 degrees at speed 5

forwards until at speed 5

backwards until at speed 5

spin left until at speed 5

spin right until at speed 5

set both motors to drive forwards at speed 5

set right motor to forwards at speed 5

set left motor to forwards at speed 5

Start

forwards for 1.05 seconds at speed 5

- Drive
- Data
- Sensing
- LEDs
- Events
- Operators
- Sound
- Control
- Comment

```
backwards for 1 cm at speed 5
```

```
spin left for 1 degrees at speed 5
```

```
spin right for 1 degrees at speed 5
```

```
forwards until at speed 5
```

```
backwards until at speed 5
```

```
spin left until at speed 5
```

```
spin right until at speed 5
```

```
set both motors to drive forwards at speed 5
```

```
set right motor to forwards at speed 5
```

```
set left motor to forwards at speed 5
```

```
stop both motors
```

```

Start
forwards for 0.5 seconds at speed 5
  spin left for 90 degrees at speed 5
forwards for 0.5 seconds at speed 5
  spin left for 90 degrees at speed 5
forwards for 0.5 seconds at speed 5
  spin right for 90 degrees at speed 5
forwards for 0.5 seconds at speed 5
stop both motors

```