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forwards for 1 cm at speed 5

backwards for 1 cm at speed 5

spin left for 1 degrees at speed 5

spin right for 1 degrees at speed 5

forwards until at speed 5

backwards until at speed 5

spin left until at speed 5

spin right until at speed 5

set both motors to drive forwards at speed 5

set right motor to forwards at speed 5

set left motor to forwards at speed 5

Start

set DriveLength to 1

repeat 10

set both motors to drive forwards at speed 5

wait $DriveLength + 200$ milliseconds

increment DriveLength

spin right for 90 degrees at speed 5