

- Drive
- Data
- Sensing
- LEDs
- Events
- Operators
- Sound
- Control
- Comment

```
backwards for 1 cm at speed 5
spin left for 1 degrees at speed 5
spin right for 1 degrees at speed 5
forwards until at speed 5
backwards until at speed 5
spin left until at speed 5
spin right until at speed 5

set both motors to drive forwards at speed 5
set right motor to forwards at speed 5
set left motor to forwards at speed 5
stop both motors
```

```
Start
set SquareSideLength to 500 * random number between 1 and 6
repeat 4
  set both motors to drive forwards at speed 5
  wait SquareSideLength milliseconds
  turn forwards right for 90 degrees at speed 5
```